# New Calabi-Yau manifolds with small Hodge numbers

#### Philip Candelas<sup>1</sup>, Rhys Davies<sup>2</sup>

 $^1{\rm Mathematical}$  Institute, University of Oxford  $^2{\rm Rudolf}$  Peierls Centre for Theoretical Physics, University of Oxford

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# Outline

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- Motivation
- The Plan of Attack
- 2 Technical Background
  - CICY's
  - Quotients of CICY's
  - Conifold transitions

#### 3 Results

- $\mathbb{Z}_5$  quotients
- $\mathbb{Z}_3$  quotients
- ${\scriptstyle \bullet}$  Quotients by  ${\mathbb H}$
- Notable points

Motivation The Plan of Attack

#### Calabi-Yau manifolds

- For this talk, a Calabi-Yau manifold is a compact Kähler 3-fold with trivial first Chern class.
- This is enough to determine all except two Hodge numbers. The Hodge diamond is

$$\begin{array}{cccccccc} h^{00} & 1 \\ h^{10} & h^{01} & 0 & 0 \\ h^{20} & h^{11} & h^{02} & 0 & h^{11} & 0 \\ h^{30} & h^{21} & h^{12} & h^{03} & = & 1 & h^{21} & h^{21} & 1 \\ h^{13} & h^{22} & h^{31} & 0 & h^{11} & 0 \\ h^{23} & h^{32} & 0 & 0 \\ h^{33} & 1 \end{array}$$

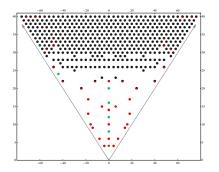
• Thus the Euler number is  $\chi = 2(h^{11} - h^{21})$ .

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Motivation The Plan of Attack

#### Triadophilia I

In a recent paper<sup>1</sup>, it was observed that the bottom of the Calabi-Yau 'landscape' is relatively sparsely populated.



 $\bullet\,$  The Kreuzer–Skarke list, CICY's, toric CICY's, and toric conifolds, with their mirrors.

• The Gross–Popescu, Rødlandand, Tonoli , Borisov-Hua and Hua manifolds.

• Previously known quotients by freely acting groups and their mirrors.

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Divided dots denote overlays.

<sup>1</sup>Candelas et al, *Triadophilia: A Special Corner in the Landscape*, **Adv.Theor.Math.Phys.12:2,2008**, arXiv:0706.3134 ( D ) ( D ) ( D ) ( D )

Motivation The Plan of Attack

# Triadophilia II

A number of other observations were made in the paper:

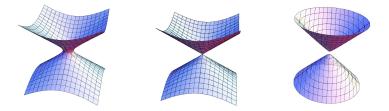
- There are at least two phenomenologically promising string models on manifolds in the 'tip', despite the scarcity of such manifolds.
- Almost all the manifolds known with small Hodge numbers have non-trivial fundamental group.

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#### Conifold transitions

• A smooth manifold can be deformed until nodes develop, and these nodes resolved to yield another manifold with the same fundamental group. This is called a "conifold transition".



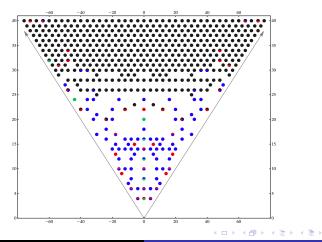
Motivation The Plan of Attack

- Therefore perhaps we can find new manifolds in the tip via conifold transitions from those which are already known.
- This corresponds to finding a conifold of the covering space which respects the symmetry.

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We can plot the distribution of Hodge numbers in the tip including the new manifolds we have found



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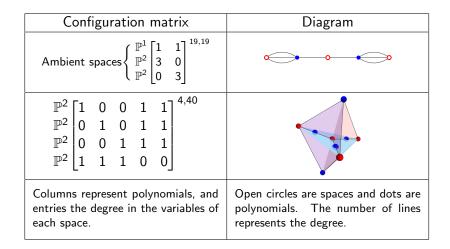
CICY's Quotients of CICY's Conifold transitions

- There are many constructions of Calabi-Yau manifolds; we need only the simplest, the Complete Intersection Calabi-Yau manifolds (CICY's).
- These are the common vanishing locus of some set of polynomials in a product of complex projective spaces.

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#### Configurations and diagrams Two examples

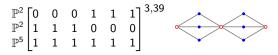


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#### Quotient manifolds An example

• Consider the configuration



Take coordinates u<sub>i</sub> on the first P<sup>2</sup>, v<sub>i</sub> on the second, and (x<sub>i</sub>, y<sub>j</sub>) on P<sup>5</sup>. Then we can define an action of Z<sub>3</sub>:

$$S: u_i \rightarrow u_{i+1}, v_i \rightarrow v_{i+1}, (x_i, y_j) \rightarrow (x_{i+1}, y_{j+1})$$

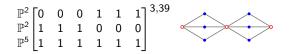
• We want our manifold invariant, so choose our polynomials such that

$$S: p_i \rightarrow p_{i+1}, q_i \rightarrow q_{i+1}$$

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CICY's Quotients of CICY's Conifold transitions

#### Quotient manifolds An example



• The appropriate polynomials are (here  $i \in \mathbb{Z}_3$ )

$$p_i = \sum_{jk} (A_{jk} x_{i+j} + B_{jk} y_{i+j}) u_{i+k}$$
  
 $q_i = \sum_{jk} (C_{jk} x_{i+j} + D_{jk} y_{i+j}) v_{i+k}$ 

 The group acts without fixed points, so we obtain a smooth quotient manifold.

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CICY's Quotients of CICY's Conifold transitions

# The conifold

• Consider the CICY given by the configuration

and take coordinates  $\{x\}$  on the first  $\mathbb{P}^2$  and  $\{y\}$  on the second.

 $\mathbb{P}^2 \begin{bmatrix} 3 \\ \mathbb{P}^2 \end{bmatrix}$ 

• We will look at a degenerate form of the defining equation:

$$U(x)V(y) - W(x)Z(y) = 0$$

where U, V, W, Z are cubics. The variety obviously has (nodal) singularities at points where U = V = W = Z = 0.

• Such singular varieties are known to physicists as "conifolds", since the neighbourhood of a node is a cone over  $S^3 \times S^2$ .

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• The conifold can be smoothed by a small change to the defining equation:

$$U(x)V(y) - W(x)Z(y) + \epsilon K(x,y) = 0$$

This is called a *deformation*.

• The conifold should be thought of as a limit point (as  $\epsilon \rightarrow 0$ ) of the moduli space of smooth manifolds.

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#### The conifold Resolving

• Now consider the pair of equations given by

$$\begin{pmatrix} U(x) & Z(y) \\ W(x) & V(y) \end{pmatrix} \begin{pmatrix} t_0 \\ t_1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \qquad \begin{pmatrix} \mathbb{P}^1 \\ \text{or } \mathbb{P}^2 \\ \mathbb{P}^2 \begin{bmatrix} 1 & 1 \\ 3 & 0 \\ 0 & 3 \end{bmatrix} \end{pmatrix}$$

- These have solutions iff UV WZ = 0, which is our singular equation again. Now though, when U = V = W = Z = 0, we have a whole  $\mathbb{P}^1$  of solutions parametrised by  $[t_0 : t_1]$ .
- The resulting variety, which is smooth, is called a *resolution* of the conifold.

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### Conifold transitions

Geometry			
Equation	$U(x)V(y) - W(x)Z(y)$ $+ \epsilon K(x, y) = 0$	U(x)V(y) - W(x)Z(y) = 0	$ \begin{pmatrix} U(x) & Z(y) \\ W(x) & V(y) \end{pmatrix} \begin{pmatrix} t_0 \\ t_1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} $
Family	$\mathbb{P}^2 \begin{bmatrix} 3 \\ 3 \end{bmatrix}$ Smooth	$\mathbb{P}^{2} \begin{bmatrix} 3 \\ 3 \end{bmatrix}$ Singular	$ \begin{array}{c} \mathbb{P}^1 \begin{bmatrix} 1 & 1 \\ \mathbb{P}^2 & 3 & 0 \\ \mathbb{P}^2 & 0 & 3 \end{bmatrix} \text{ Smooth } $

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# Splitting a configuration

 More generally we can introduce a P<sup>n</sup> to split a polynomial of total degree at least n + 1:

$$\mathcal{P}[M,\mathbf{c}] \rightarrow \frac{\mathbb{P}^n}{\mathcal{P}} \begin{bmatrix} \mathbf{0} & 1 & 1 & \cdots & 1 \\ M & \mathbf{c}_1 & \mathbf{c}_2 & \cdots & \mathbf{c}_{n+1} \end{bmatrix}$$

where 
$$\sum_{i} \mathbf{c}_{i} = \mathbf{c}$$
.

• For example,

$$\mathbb{P}^2_{\mathbb{P}^5} \begin{bmatrix} 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 3 \end{bmatrix} \to \mathbb{P}^2_{\mathbb{P}^5} \begin{bmatrix} 0 & 0 & 0 & 1 & 1 & 1 \\ 1 & 1 & 1 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 & 1 & 1 \end{bmatrix}$$

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Conifold transitions in string theory

- Geometrically, a conifold is singular, but in string theory, the physics is still sensible.
- So it is possible for spacetime to undergo a conifold transition!
- Seemingly distinct string vacua are therefore actually connected.

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 $\begin{array}{l} \mathbb{Z}_5 \mbox{ quotients} \\ \mathbb{Z}_3 \mbox{ quotients} \\ \mbox{ Quotients by } \mathbb{H} \\ \mbox{ Notable points} \end{array}$ 

## A quotient of the quintic

It has been known for a long time that the quintic  $\mathbb{P}^4[5]$  admits a free action by  $\mathbb{Z}_5$ . Let's see how this works:

• Take the following special case of the defining equation

$$(x_0)^5 + (x_1)^5 + (x_2)^5 + (x_3)^5 + (x_4)^5 + \alpha x_0 x_1 x_2 x_3 x_4 = 0$$

• There is a free  $\mathbb{Z}_5$  action given by  $x_i \to x_{i+1}$ .

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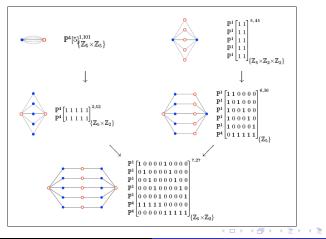
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## Splitting the quintic

We want to split the quintic in a way which might preserve this  $\mathbb{Z}_5$  symmetry. There is a natural candidate:

# The $\mathbb{Z}_5$ web

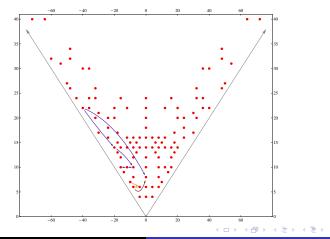
Continuing in a similar fashion, we obtain the following "web" of  $\mathbb{Z}_5$  quotients



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#### The $\mathbb{Z}_5$ web

We can also plot the conifold transitions on the Hodge numbers diagram



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The following two manifolds each admit a free  $\mathbb{Z}_3 \times \mathbb{Z}_3$  action.

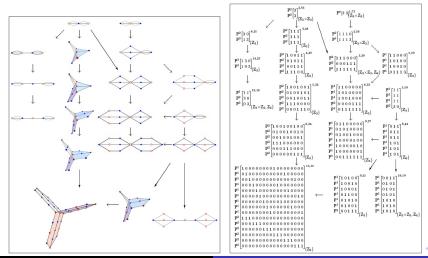


We can split each of these repeatedly to obtain the following web of manifolds admitting free  $\mathbb{Z}_3$  actions.

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#### The $\mathbb{Z}_3$ web

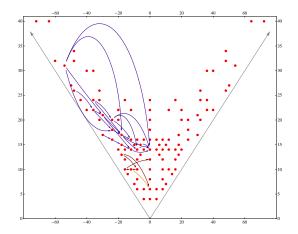


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The  $\mathbb{Z}_3$  web



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#### The quaternion group

• Finally we found free actions by the order 8 quaternion group:

$$\{1, i, j, k, -1, -i, -j, -k\}$$

 $\bullet\,$  The starting point is the following, already known to admit an  $\mathbb H$  action

$$\mathbb{P}^{7}[2 \ 2 \ 2 \ 2]^{1,65}$$



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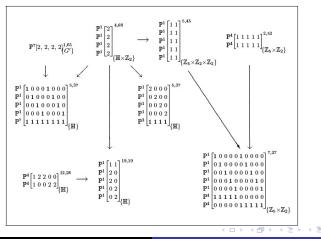
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#### The $\mathbb H$ web

By splitting the above manifold we obtain a number of new examples:



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### Matrix transposition

- For each matrix appearing in one of our webs, the transpose also appears.
- This is puzzling:
  - Transposition has no obvious geometrical meaning.
  - Even if two matrices give the same manifold, their transposes can give different manifolds.

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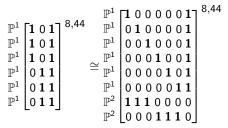
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#### Matrix transposition

Example: the following are equivalent



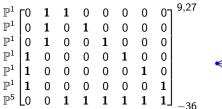
but the transposes have different Hodge numbers

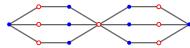
$$\mathbb{P}^{2}_{p} \begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 \\ \mathbb{P}^{2}_{p} \begin{bmatrix} 1 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \begin{bmatrix} 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 1 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 1 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 1 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ \mathbb{P}^{1}_{p} \end{bmatrix} \end{bmatrix} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0$$

 $\mathbb{Z}_5$  quotients  $\mathbb{Z}_3$  quotients Quotients by  $\mathbb{H}$ Notable points

A new  $\chi = -6$  manifold

The following occurs in the  $\mathbb{Z}_3$  web:

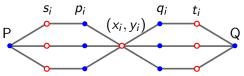




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Label coordinates and polynomials as follows (with  $i \in \mathbb{Z}_3$ )



We can then define a  $\mathbb{Z}_3{\times}\mathbb{Z}_2$  action with generators

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A new  $\chi = -6$  manifold

• *S* acts without fixed points, but the fixed points of *U* correspond to two copies of

$\mathbb{P}^1$	[1	1	0	0]
$\mathbb{P}^{1}$ $\mathbb{P}^{1}$ $\mathbb{P}^{2}$	1	0	1	0
$\mathbb{P}^1$	1	0	0	1
$\mathbb{P}^2$	0	1	1	1

- These are one-dimensional CICY's i.e. tori.
- Thus they have Euler number 0, and we can resolved them without changing the Euler number.

 $\begin{array}{l} \mathbb{Z}_5 \mbox{ quotients} \\ \mathbb{Z}_3 \mbox{ quotients} \\ \mbox{ Quotients by } \mathbb{H} \\ \mbox{ Notable points} \end{array}$ 

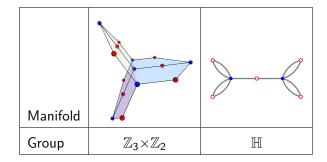
#### Euler number 0 manifolds

• The U.Penn. group has constructed a promising heterotic string model on the following manifold

$$\begin{pmatrix} \mathbb{P}^1 \begin{bmatrix} 1 & 1 \\ \mathbb{P}^2 \begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix}_{/\mathbb{Z}_3 \times \mathbb{Z}_3} \end{pmatrix}^{3,3}$$

• We now have two more manifolds with Hodge numbers 3, 3.

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These quotient manifolds both have Hodge numbers  $(h^{11}, h^{21}) = (3, 3)$ .

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- We have found a number of new multiply-connected manifolds with small Hodge numbers.
- At least two of these manifolds resemble existing manifolds on which promising string models have been contructed.
- Scope for new model building, or general study of multiply-connected manifolds in string theory.

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